

## **R-state-var-init**<sup>11,40</sup>

$\text{R-state-var-init}(i; ds; da; x; T; v; ks; tr)$

$\equiv_{\text{def}} \text{Rplus}(\text{R-state-var}(i; ds; da; x; T; ks; tr); \text{Rinit}(i; T; x; (\text{inl } v)))$